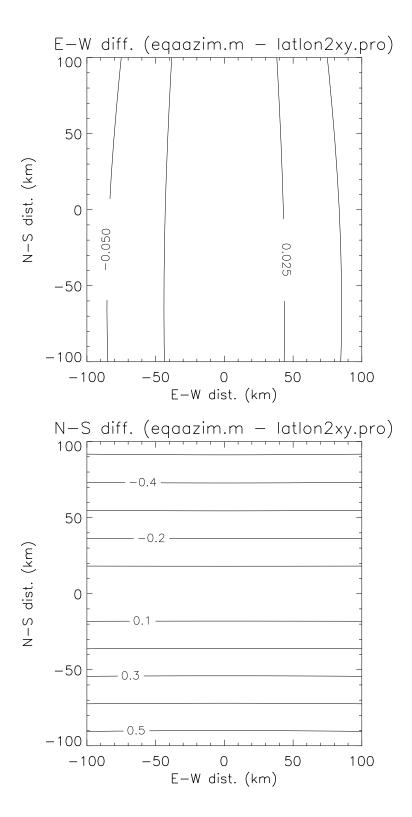
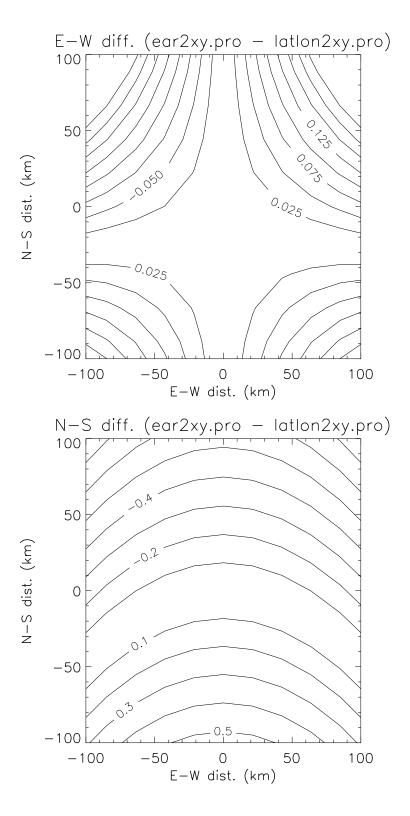
Co-location of aircraft and radar data.

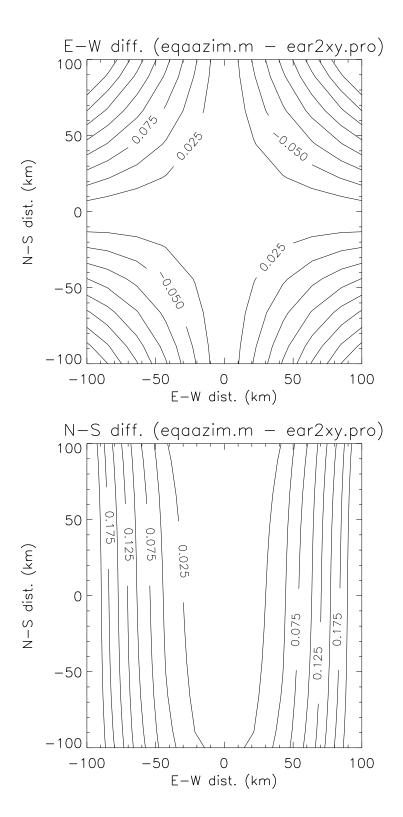
see report on //www-das.uwyo.edu/~vali/rico/rico.html for explanation; only the figures are included here



axes refer to position from eqaazim (xlab,ylab)



axes refer to position from ear2xy



axes refer to position from eqaazim (xlab,ylab)

		measured	calculated (km)		
			solo-ii/latlon2xy	eqaazim	ear2xy
20:37:51 UTC		KA GPS (note 1)			
	lat	18.1442			
	lon	-61.9730			
	xpos		-15.73	-15.73	-15.76
	ypos		59.74	59.41	59.42
		SPol via solo-ii (note 2)			
	lat		18.1395		
	lon		-61.9716		
	xpos ± 0.84 (note 4)	-15.62		-15.64	-15.67
	ypos ± 0.29	59.25		58.94	58.95
20:39:46 UTC		KA GPS (note 1)			
	lat	18.1454			
	lon	-61.9754			
	xpos		-15.98	-15.99	-16.02
	ypos		59.87	59.54	59.54
		SPol via solo-ii (note2)			
	lat		18.1409		
	lon		-61.9746		
	xpos ± 0.86	-15.94		-15.85	-15.88
	ypos ± 0.36	59.38		59.16	59.17

note 1: King Air GPS data taken from 1-Hz file, reading a single value without smoothing

note 2: for hit at 20:37:51, using data from one of the two (the Eastern one) pixels with equal reflectivity (36 dBZ)

for hit at 20:39:46, using center of four adjacent pixels (33, 37, 41, 46 dBZ)

note 3: using the difference between the GPS and SPol values via 'ear2xy'

note 4: radar pixel size is 0.8° in azimuth and 0.15 km in range